Solving System of Linear Equations Hung-yi Lee

Reference

• Textbook: Chapter 1.3, 1.4

九章算術 秉 御 錯 唐 糅 IE 省 木 李 劉 厚 風 徽 置 | 禾-秉,中禾二秉,下禾-秉,實-十 九斗,於右方。中、左禾列如右方。以右行 中 注 上禾遍乘中行而以百除。又乘其次 亦以百 禾 除。然以中行中禾不盡者遍乘左行而以首除 實即下 左方卜禾��霊者,卜為法,卜 為貫 o 原 禾之實。求中禾,以法乘中行下實 令 ,而除下 禾之雷 。餘如中禾秉數而-即中禾之實 0 上禾亦以法乘右行下��,而除下禾、中禾 求 之實。餘如上禾秉數而一, 即上禾之實。實 不 報 木 皆如法,各得一斗。

算法統宗

	與奇行認莫差若過奇行須減慣偶行之價層方程法可誇須存末位作根芽諸行乗減同前
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Equivalent

 Two systems of linear equations are equivalent if they have exactly the same solution set.

$$\begin{cases} 3x_1 + x_2 = 10 \\ x_1 - 3x_2 = 0 \end{cases}$$
Solution set:
$$\{ \begin{bmatrix} 3 \\ 1 \end{bmatrix} \}$$
equivalent
$$\begin{cases} x_1 = 3 \\ x_2 = 1 \end{cases}$$
Solution set:
$$\{ \begin{bmatrix} 3 \\ 1 \end{bmatrix} \}$$

Equivalent

- Applying the following three operations on a system of linear equations will produce an equivalent one.
- 1. Interchange

$$\begin{cases} 3x_1 + x_2 &= 10 \\ x_1 - 3x_2 &= 0 \end{cases} \implies \begin{cases} x_1 - 3x_2 &= 0 \\ 3x_1 + x_2 &= 10 \end{cases}$$

• 2. Scaling

$$\begin{cases} 3x_1 + x_2 = 10 \\ x_1 - 3x_2 = 0 \\ x_1 - 3x_2 = 0 \\ x_1 - 3x_2 = 0 \end{cases} \implies \begin{cases} 3x_1 + x_2 = 10 \\ -3x_1 + 9x_2 = 0 \\ x_1 - 3x_2 = 0 \end{cases}$$

• 3. Row Addition

$$\begin{cases} 3x_1 + x_2 = 10 \\ x_1 - 3x_2 = 0 \\ x_1 - 3x_2 = 0 \\ x_1 - 3x_2 = 0 \end{cases} \Rightarrow \begin{cases} 10x_2 = 10 \\ x_1 - 3x_2 = 0 \\ x_1 - 3x_2 = 0 \end{cases}$$

Solving system of linear equation

 Two systems of linear equations are equivalent if they have exactly the same solution set.

• Strategy:

We know how to transform the given system of linear equations into another equivalent system of linear equations.

We do it again and again until the system of linear equation is so simple that we know its answer at a glance.

Augmented Matrix

a system of linear equation

 $\begin{array}{rcl} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n &=& b_1 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n &=& b_2 \\ \vdots & & & & & & & & & & \\ \end{array}$

 $a_{m1}\mathbf{x_1} + a_{m2}\mathbf{x_2} + \dots + a_{mn}\mathbf{x_n} = b_m$

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix} \quad x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \quad b = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}$$
coefficient matrix

Augmented Matrix

a system of linear equation

Solving system of linear equation

- Two systems of linear equations are equivalent if they have exactly the same solution set.
- Strategy of solving:



- 1. Interchange any two rows of the matrix
- 2. Multiply every entry of some row by the same nonzero scalar
- 3. Add a multiple of one row of the matrix to another row

Solving system of linear equation



- 1. Interchange any two rows of the matrix
- 2. Multiply every entry of some row by the same nonzero scalar
- 3. Add a multiple of one row of the matrix to another row

elementary row operations

- A system of linear equations is easily solvable if its augmented matrix is in *reduced row echelon form*
- Row Echelon Form

- 1. Each nonzero row lies above every zero row
- 2. The leading entries are in echelon form



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No zero rows

- A system of linear equations is easily solvable if its augmented matrix is in *reduced row echelon form*
- Reduced Row Echelon Form
 - 1-2 The matrix is in row echelon form
 - 3. The columns containing the leading entries are standard vectors.



- A system of linear equations is easily solvable if its augmented matrix is in *reduced row echelon form*
- Reduced Row Echelon Form
 - 1-2 The matrix is in row echelon form
 - 3. The columns containing the leading entries are standard vectors.



RREF is unique

• A matrix can be transformed into multiple REF by row operation, but only one RREF







The pivot positions of A are (1,1), (2,3) and (3,4). The pivot columns of A are 1st, 3rd and 4th columns.

 A system of linear equations is easily solvable if its augmented matrix is in *reduced row echelon form*

Example 1. Unique Solution



If RREF looks like [*I* **b**']

unique solution

Example 2. Infinite Solution



Parametric Representation:

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 7+3x_2-2x_4 \\ 9-6x_4 \\ 2 \end{bmatrix}$$

• Example 3. No Solution



When an augmented matrix contains a row in which **the only nonzero entry lies in the last column**



The corresponding system of linear equations has **no solution (inconsistent).**

http://www.ams.org/notices/201106/rtx110600782p.pdf http://www.dougbabcock.com/matrix.php

Reduced Row Echelon Form

- RREF of a matrix is unique.
- Gaussian elimination: an algorithm for finding the reduced row echelon form of a matrix.



Please refer to the steps of Gaussian Elimination in the textbook by yourself.









$$\begin{bmatrix} 1 & 2 & -1 & 2 & 1 & 2 \\ 0 & 0 & -1 & -2 & -2 & -1 \\ 0 & 0 & 0 & 4 & 4 & 8 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & -1 & 0 & -1 & -2 \\ 0 & 0 & -1 & 0 & 0 & 3 \\ 0 & 0 & 0 & 1 & 1 & 2 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$





$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} -5 - 2x_2 + x_5 \\ x_2 \\ -3 \\ 2 - x_5 \\ x_5 \end{bmatrix} = x_2 \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_5 \begin{bmatrix} 1 \\ 0 \\ 0 \\ -1 \\ 1 \end{bmatrix} + \begin{bmatrix} -5 \\ 0 \\ -3 \\ 2 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} x_{1} \\ x_{2} \\ x_{3} \\ x_{4} \\ x_{5} \end{bmatrix} = \begin{bmatrix} -5 - 2x_{2} + x_{5} \\ x_{2} & 1 \\ -3 \\ 2 - x_{5} & 3 \\ x_{5} & -1 \end{bmatrix}^{-8} = \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \\ 0 \\ -1 \\ 1 \end{bmatrix} + \begin{bmatrix} -5 \\ 0 \\ -3 \\ 2 \\ 0 \end{bmatrix}$$

$$x_{1} free \\ x_{2} = -\frac{5}{2} - \frac{1}{2}x_{1} + \frac{1}{2}x_{5} \\ x_{1} = -5 - 2x_{2} + x_{5} - \frac{1}{2}x_{1} + \frac{1}{2}x_{5} \\ x_{1} = -5 - 2x_{2} + x_{5} - \frac{1}{2}x_{1} + \frac{1}{2}x_{5} \\ x_{1} = -5 - 2x_{2} + x_{5} - \frac{1}{2}x_{1} + \frac{1}{2}x_{5} \\ x_{2} = -\frac{5}{2} - \frac{1}{2}x_{1} + \frac{1}{2}x_{5} \\ x_{1} = -5 - 2x_{2} + x_{5} - \frac{1}{2}x_{1} + \frac{1}{2}x_{5} \\ x_{2} = -\frac{5}{2} - \frac{1}{2}x_{1} + \frac{1}{2}x_{5} \\ x_{3} = -3 \\ x_{4} = 2 - x_{5} \\ x_{5} & \text{free} \end{bmatrix}$$

$$x_{1} = \begin{bmatrix} -5/2 - \frac{x_{1} - 8}{1/2} \\ -3 \\ 2 - x_{5} & 3 \\ x_{5} - 1 \end{bmatrix} = \begin{bmatrix} -5/2 - \frac{x_{1} - 8}{1/2} \\ -3 \\ 2 - x_{5} & 3 \\ x_{5} - 1 \end{bmatrix} = \begin{bmatrix} -\frac{8}{2}x_{1} \\ -\frac{1}{2}x_{2} \\ 0 \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ 1/2 \\ 0 \\ -1 \\ 1 \end{bmatrix} + \begin{bmatrix} 0 \\ -5/2 \\ -3 \\ 2 \\ 0 \end{bmatrix}$$

• Find the RREF of

$$R = \begin{bmatrix} 1 & 0 & -3 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & -3 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 2 & 0 & -6 & 0 \\ 0 & 2 & 4 & 0 \\ 0 & 0 & 0 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$



• Find the RREF of $\begin{bmatrix} R & 2R \\ R & -R \end{bmatrix}$ $R = \begin{bmatrix} 1 & 0 & -3 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$

$$\begin{bmatrix} R & 2R \\ R & -R \end{bmatrix} \rightarrow \begin{bmatrix} R & 2R \\ \mathbf{0} & -3R \end{bmatrix} \begin{bmatrix} 1 & 0 & -3 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 2 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & -3 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & -3 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Checking Independence $S = \left\{ \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 4 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \right\}$ Linear independent or not?

A set of n vectors $\{a_1, a_2, ..., a_n\}$ is linear dependent

Given a vector set, $\{\mathbf{a}_1, \mathbf{a}_2, ..., \mathbf{a}_n\}$, if there exists any \mathbf{a}_i that is a linear combination of other vectors

matrix A

Given a vector set, $\{\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_n\}$, there exists scalars $\underline{x}_1, \underline{x}_2, \dots, \underline{x}_n$, that are **not all zero**, such that $x_1\mathbf{a}_1 + x_2\mathbf{a}_2 + \dots + x_n\mathbf{a}_n = \mathbf{0}$. Vector **x**

x = 0 have non-zero solution



Checking Independence



 $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} -2x_3 \\ x_3 \\ x_3 \\ 0 \end{bmatrix} = x_3 \begin{bmatrix} -2 \\ 1 \\ 1 \\ 1 \\ 0 \end{bmatrix} \text{ setting } x_3 = 1 \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} -2 \\ 1 \\ 1 \\ 0 \end{bmatrix}$